

Invariant Polymorphism in Virus Capsid Assembly

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Abstract: Directed self-assembly of designed viral capsids holds significant potential for applications in materials science and medicine. However, the complexity of preparing these systems for assembly and the difficulty of quantitative experimental measurements on the assembly process have limited access to critical mechanistic questions that dictate the final product yields and isomeric forms. Molecular simulations provide a means of elucidating self-assembly of viral proteins into icosahedral capsids and are the focus of the present study. Using geometrically realistic coarse-grained models with specialized molecular dynamics methods, we delineate conditions of temperature and coat protein concentration that lead to the spontaneous self-assembly of $T = 1$ and $T = 3$ icosahedral capsids. In addition to the primary product of icosahedral capsids, we observe a ubiquitous presence of nonicosahedral yet highly symmetric and enclosed aberrant capsules in both $T = 1$ and $T = 3$ systems. This polymorphism in assembly products recapitulates the scope and morphology of particle types that have been observed in mis-assembly experiments of virus capsids. Moreover, we find that this structural polymorphism in the end point structures is an inherent property of the coat proteins and arises from condition-dependent kinetic mechanisms that are independent of the elemental mechanisms of capsid growth (as long as the building blocks of the coat proteins are all monomeric, dimeric, or trimeric) and the capsid T number. The kinetic mechanisms responsible for self-assembly of icosahedral capsids and aberrant capsules are deciphered; the self-assembly of icosahedral capsids requires a high level of assembly fidelity, whereas self-assembly of nonicosahedral capsules is a consequence of an off-pathway mechanism that is prevalent under nonoptimal conditions of temperature or protein concentration during assembly. The latter case involves kinetically trapped dislocations of pentamer-templated proteins with hexameric organization. These findings provide insights into the complex processes that govern viral capsid assembly and suggest some features of the assembly process that can be exploited to control the assembly of icosahedral capsids and nonicosahedral capsules.

Introduction

The spontaneous self-assembly of identical protein units into complex but highly regular icosahedral capsid shells,^{1,2} which protect the packaged viral genome, has motivated studies in virology for decades. More recently, viral capsids have been considered the ultimate biologically ordered system at the nanoscale level, with beneficial applications emerging in materials science and medicine.³ For example, empty viral capsids of the human papilloma virus serve as cervical cancer vaccines,⁴ where potency depends strongly upon the degree of capsid self-assembly.⁵ The inability to control assembly in laboratory and manufacturing procedures leads to architectural contaminants (i.e., structural polymorphism).⁶ A clear understanding of the kinetic mechanisms and thermodynamic control of capsid self-

assembly would provide invaluable insights into controlled self-assembly of icosahedral capsids and serve as a crucial prerequisite to their widespread application in medicine and bionanotechnology.

In recent years, substantial progress has been made via a plethora of experimental, modeling, and simulation-based studies^{7–20} in regards to capsid self-assembly in general. Kinetic insights have been obtained from several studies^{8,16–18} that examine the formation of icosahedral capsids which are formed with a high degree of absolute assembly fidelity. However, there are only a few studies that focus on the self-assembly of

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nonicosahedral capsids,^{21–23} and the kinetic mechanism for the formation of nonicosahedral capsids that coexist with icosahedral capsids (e.g., different oblong flock house virus particles observed by Dong et al.)²⁴ remains unknown. The present computational study was designed to augment this knowledge with the aim of optimizing experimental designs.

It is well recognized that the coat protein shape plays an important role in the organization of the closed icosahedral structure. Statistically, coat proteins largely comprise a conserved β -barrel motif with a trapezoidal shape, even though they are chemically distinct, that is found in a wide variety of virus families sharing little-to-no host, size, or amino acid sequence similarity.^{25,26} Mathematically, it has been recently proven that the trapezoidal shape is the perfect building block to tile a closed icosahedral surface of any capsid size.²⁷ Exploiting this important role of the coat protein shape and the observation that the driving forces for capsid assembly arise from weak noncovalent interprotein interactions of 3–4 kcal/mol,^{28,29} we developed coarse-grained models (Figure 1) that represent each coat protein as a trapezoidal structure with interprotein interactions described by generalized short-ranged, weak, and anisotropic attractions. Our coat protein models represent each protein subunit as a set of 24 beads arranged in four layers confined in the trapezoidal geometry. These models contain significantly more protein detail than models that represent each coat protein, capsomer, or vertex as a single spherical bead with directional bondings or as a patchy particle suitable for the formation of $T = 1$ capsids.^{14,16,17,19,20} Our geometric models are inspired by the approach of Rapaport et al.,^{12,30} who performed the first exploratory molecular dynamics simulations on capsid self-assembly of a polyhedral structure from trapezoidal subunits. Unlike these early simulations, which enforced many nonphysical assembly rules ensuring that only complete capsids would be formed and thus could not probe or capture the spontaneous and reversible nature of capsid self-assembly, our simulations proceed without any built-in self-assembly rules. Coupled with discontinuous molecular dynamics, an extremely fast alternative to traditional molecular dynamics, our models allow us to simulate the spontaneous self-assembly of not only $T = 1$ and

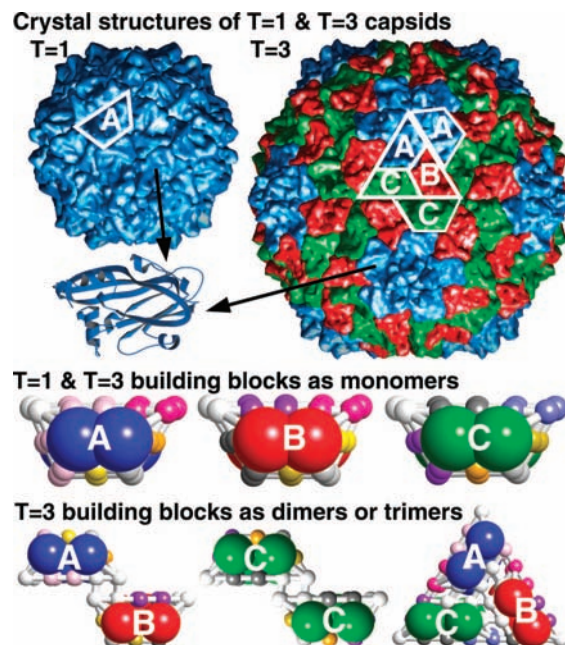


Figure 1. Coarse-grained models of coat proteins as monomers for $T = 1$ and $T = 3$ systems; models of coat proteins as dimers and trimers are also employed for $T = 3$ systems. Our monomer models capture the basic trapezoidal shape of a typical coat protein from crystal structures.⁴⁰ A $T = 1$ icosahedral capsid is comprised of 60 coat proteins of the same type (A-subunit) arranged in 12 pentamers while a $T = 3$ icosahedral capsid contains 180 coat proteins of three different types (A-, B-, and C-subunits, in equal number) arranged as 12 pentamers of A-subunits and 20 hexamers of B- and C-subunits. Subunits of the A-type are templated for pentamer formation, and B- and C-subunits are templated for hexamer formation. The dimer models represent capsomers of either A- and B-subunits or C- and C-subunits; the trimer models represent capsomers of A-, B-, and C-subunits. The top and bottom layers of each subunit contain hard spheres providing volume exclusion. To account for autostery,³¹ specific intersubunit interactions are allowed between pseudoatoms of the same, nonwhite, color on similar middle layers. When two subunits are perfectly aligned at the correct angle forming a maximum number of four attractive interactions, the resulting interface is considered “native”; a “non-native” interface can occur when two subunits are locked at a wrong angle forming a fewer number of attractive interactions. Molecular dynamics simulations were carried out at constant temperature in a fixed volume with periodic boundary conditions without any built-in self-assembly rules starting from a random configuration of exclusively monomers, dimers, or trimers as the building blocks.

$T = 3$ icosahedral capsids but also nonicosahedral capsids, which requires significantly longer simulation times to observe and study.

We explore the assembly of $T = 1$ and $T = 3$ capsids, where T (triangulation number) denotes the number of subunits constituting an icosahedral asymmetric unit ($T = 1, 3, 4, 7$, etc.) and the number of copies of the same coat protein (i.e., $60T$ proteins that are arranged as twelve pentamers and $10(T - 1)$ hexamers at well-defined locations).² Protein subunits of only one conformation (i.e., pentamer-forming A-subunits) are needed to form $T = 1$ capsids, whereas subunits of three different conformations (i.e., pentamer-forming A-subunits and hexamer-forming B- and C-subunits) are needed to form $T = 3$ capsids. Since all protein subunits (gene products) are chemically identical,³¹ the switching of coat proteins between conformations that are poised to form either a pentameric or hexameric capsomer in $T \geq 3$ systems must occur during assembly. High-resolution *in vitro* studies,³² in which robust assembly by capsid

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subunits readily occurs to reconstitute empty icosahedral capsids with a morphology indistinguishable from those virus particles assembled *in vivo*, reveal that the variations in protein conformations involve an alteration between order and disorder of the flexible regions located near the N- and C-termini, which are commonly referred to as molecular switches.^{33,34} When ordered, these arms interdigitate with their neighbors serving as wedges between proteins that are arranged in a hexamer; therefore, the angle between these wedged proteins along the 6-fold symmetry axis is relatively flat, whereas the angle between nonwedged proteins along the 5-fold symmetry axis is relatively sharp. The exact nature of how this conformational switching mechanism (also known as autostery) takes place in deciding the appropriate conformation that is needed for adding onto the growing capsid at the right location is not well understood. Since the switching time scale is unknown but is local in nature, it may be anticipated to be facile compared to the time scales of protein assembly. Consequently, in constructing our models, we assume that a switching step is much faster than an assembly step and thus our simulations proceed from a pre-equilibrium of pentamer-templated and hexamer-templated protein units. Given the quasi 3-fold symmetry of $T = 3$ viral capsids, this gives rise to equal numbers of subunits in three predetermined conformations. Although the molecular switch is not explicitly represented in our models, its effect in flattening the dihedral angle between B- and C-subunits in hexamers is taken into account. Specifically, the trapezoidal geometry of the three model subunits accommodates the acute dihedral angle of 144° between A-subunits (or between B- and C-subunits) along the 5-fold symmetry axis and a relatively flat angle of 170° between B- and C-subunits along the 6-fold symmetry axis. Moreover, to account for the role of autostery in regulating the addition of a subunit of a certain conformation onto the growing structure during assembly at the right location, we impose specific interactions between certain subunits at the appropriate interfaces. A-subunits are allowed to form interfacial interactions at the 5-fold symmetry axis, whereas B- and C-subunits at the 6-fold symmetry axis and the three subunits are allowed to form interfacial interactions at the 3-fold symmetry axis. In effect, imposing specific interactions allows the formation of pentamers and hexamers at the right locations; for instance, when a pentamer of A-subunits is formed first, only B- and C-subunits are added at the surrounding locations so that only hexamers can be grown.

We utilize molecular dynamics simulations to analyze molecular-level kinetic events that are difficult or impossible to explore experimentally during the self-assembly process. Molecular dynamics simulations were carried out at constant temperature in a fixed volume with periodic boundary conditions starting from a random configuration of exclusively monomers (i.e., A-subunits in $T = 1$ systems and A-, B-, and C subunits in $T = 3$ systems) as the building blocks. Since the starting building blocks of many virus assembly systems have been shown to be dimeric³⁵ or trimeric,²⁴ we also performed simulations starting from a stoichiometric mixture of dimers that are derived from A–B subunits and C–C subunits, which are rigidly coupled together at the 2-fold interface. Similarly,

we also performed simulations starting from a configuration of trimers that are derived from A-, B-, and C-subunits, which are rigidly coupled together at the 3-fold interface. We examine and contrast the kinetics and thermodynamics governing spontaneous capsid self-assembly in $T = 1$ and $T = 3$ capsid systems under optimal conditions in which the icosahedral symmetry rule is obeyed. Moreover, we explore suboptimal conditions where the icosahedral symmetry rule breaks resulting in the formation of aberrant structures other than canonical icosahedral capsids. Based on these insights, we formulate strategies for the controlled assembly of icosahedral capsids and other nonicosahedral capsules by fine-tuning the conditions and redesigning the coat proteins.

Methods

Our coarse-grained models (Figure 1), which capture the basic trapezoidal shape of a typical coat protein from $T = 1$ and $T = 3$ crystal structures, are used with discontinuous molecular dynamics (DMD),³⁶ an extremely fast alternative to traditional molecular dynamics. In the DMD simulation algorithm all potentials are discontinuous, i.e., based on hard-sphere or square-well interactions. The solvent is modeled implicitly in the sense that interprotein interactions represent solvent renormalized interactions. The excluded volume of each pseudoatom is modeled using a hard-sphere potential. Covalent bonds are maintained between adjacent pseudoatoms by imposing hard-sphere repulsions whenever the bond lengths fluctuate outside of the range $(1 - \delta)L$ and $(1 + \delta)L$, where L is the bond length and δ represents bond fluctuation and is 20% of L . These fluctuations mimic the conformational flexibility anticipated for individual protein subunits. Interactions between attractive sites are represented by a square well of depth ϵ and range 1.5σ , where σ is the pseudoatom diameter. For details of the DMD methodology, see papers by Alder and Wainwright³⁶ and Smith, Hall, and Freeman.³⁷

All simulations were performed in the canonical ensemble with periodic boundary conditions imposed to eliminate artifacts due to the box edges. Constant temperature is achieved through the Andersen thermostat method.³⁸ With this procedure, all pseudoatoms in the simulation are subject to random hard-sphere collisions with imaginary heat-bath particles called ghost particles.³⁹ The postevent velocity of a pseudoatom colliding with a ghost particle is chosen randomly from a Maxwell–Boltzmann distribution at the simulated temperature. Simulation temperature is expressed in terms of the reduced temperature ($T^* = k_B T_{\text{sim}}/\epsilon$, where k_B is Boltzmann's constant, T_{sim} is the temperature, and ϵ is the basic interaction strength) and reduced time ($t^* = t\sigma(k_B T_{\text{sim}}/m)^{1/2}$, where t is the simulation time and m is the pseudoatom mass).

The results presented in this paper are from averages over 100 independent simulations at each condition unless specified otherwise. Each $T = 1$ simulation was performed on a system containing 1500 protein subunits, which can form up to 25 complete $T = 1$ capsids. Each $T = 3$ system contains 1800 monomeric subunits, 900 dimeric subunits, or 600 trimeric subunits, which can form up to 10 complete $T = 3$ capsids. Each system was simulated over a wide range of temperatures and simulation box sizes (protein concentrations). The resulting protein concentrations were estimated to be $c = 21.7, 43.25, 86.5,$ and $173 \mu\text{M}$ using the average dimension of coat proteins in crystal structures of small viral capsids.⁴⁰ Our range of temperatures between $T^* = 0.30$ and 0.50

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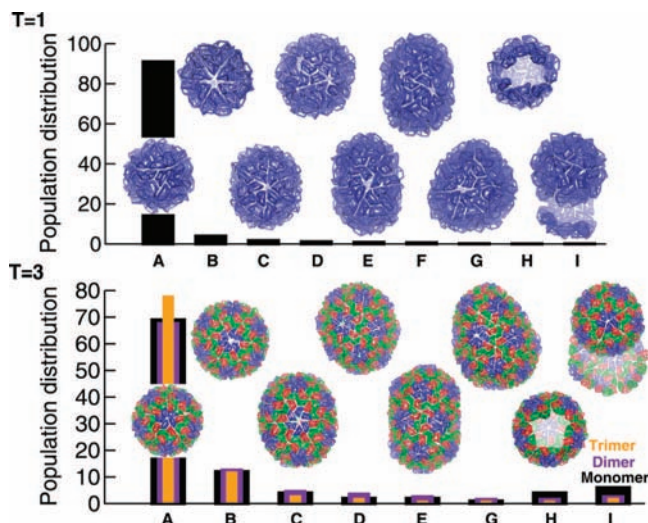


Figure 2. Population distribution obtained from 100 simulations for the $T = 1$ system at $86.5 \mu\text{M}$ and 290 K and the $T = 3$ system at $86.5 \mu\text{M}$ and 308 K : (A) complete icosahedral capsid, (B) oblate capsule, (C) angular capsule, (D) twisted capsule, (E) tubular capsule, (F) prolate capsule, (G) conical capsule, (H) partial capsid, and (I) open mis-aggregate. The population distribution for supramolecular structures from $T = 3$ systems containing coat proteins represented as either monomers (black), dimers (purple), or trimers (orange) is shown.

is equivalent to 264 and 440 K, respectively, estimated using the value -3.5 kcal/mol as the average protein intersubunit interaction free energy as extracted from experiments on Hepatitis B virus capsids²⁸ (-3 to -4 kcal/mol) and cowpea chlorotic mottle virus capsids²⁹ (about -3 kcal/mol). Although our systems are relatively large, containing over 36 000 pseudoatoms for the $T = 1$ model or 43 200 pseudoatoms for the $T = 3$ models, they explore the complete assembly process starting from a random configuration and arriving at an equilibrium configuration that exhibits a variety of ordered and disordered structures, depending on the simulation conditions. The simulation time required to see the first complete capsid was relatively short, involving only a few days on a single-processor workstation. However, each system was simulated for a long period of time (about 30 days of CPU time) until the ensemble average of the total potential energy varied by no more than 2.5% during the last three-fourths of each simulation run.

Results

Observation of Icosahedral Capsids and Nonicosahedral Capsules at Near-Optimal Conditions. Under the conditions of protein concentration at $86.5 \mu\text{M}$ and temperature at 308 K , assembly efficiency approaches 95 % for 60-subunit, $T = 1$ capsids. However, the optimum conditions for $T = 1$ capsid assembly produce a lower yield of $< 80 \%$ for 180-subunit, $T = 3$ capsids; rotation function analysis⁴¹ verifies that these complete capsids (Figure 2A) are indeed icosahedral (SI, Figure 7). It is remarkable that these precise structures spontaneously form given that assembly of complete capsids, even though an enthalpically driven process, is kinetically hindered. In previous studies, we demonstrated that although the early assembly steps take place on a downhill free-energy landscape, insertion of the final subunits is slow and can be rate-limiting.¹⁸ Moreover, one misstep, e.g., the formation of a single non-native protein–protein interface out of 150 ($T = 1$) or 450 ($T = 3$) native interfaces, can derail the assembly and cause the system to form other nonidealized structures.

Self-assembly of icosahedral capsids is strongly dependent upon the assembly conditions. In fact, slightly lowering the temperature from 308 to 290 K at $86.5 \mu\text{M}$ leads to polymorphism in $T = 1$ assembly studies. At this temperature, in addition to icosahedral capsids, we observe a variety of nonicosahedral capsules that are enclosed and highly symmetric (Figure 2B–F). Similar to icosahedral capsids, nonicosahedral capsules contain 12 pentamers (required for structure closure) that are evenly distributed around each structure. The capsules are larger than the icosahedral $T = 1$ capsids, containing a precise number of $N = 60 + 6D$ monomeric subunits where D is the number of hexameric “dislocations”. The dislocations are comprised of kinetically trapped pentamer-templated A-subunits in a hexavalent environment. The relative position and number of hexameric dislocations define each capsule type: D -values of 2, 3, 4, 5, and 6 correspond to oblate, angular, twisted, tubular, and prolate capsules, respectively. The oblate and twisted capsules are semispherical, whereas angular, tubular, and prolate capsules are elongated. We also observe the formation of nonsymmetric structures called conical capsules (Figure 2G), where 12 pentamers are unevenly distributed in the structure (i.e., five pentamers are on one end of the structure while seven are localized on the other end).

The same sort of structural polymorphism is also observed in the $T = 3$ system at $86.5 \mu\text{M}$ and 308 K (Figure 2). Besides icosahedral capsids, nonicosahedral yet completely enclosed structures such as oblate (Mov. S1), angular (Mov. S2), twisted (Mov. S3), and tubular (Mov. S4) capsules containing $N = 180 + 18D$ monomeric subunits, where D -values are 2–5, are observed. The dislocations are comprised of kinetically trapped pentamer-templated A-subunits in a strained conformation where at least one subunit makes suboptimal interactions with its neighbors: in each hexameric dislocation A-subunits make fewer interactions than a spontaneously formed hexamer of B- and C-subunits. Pentameric dislocations containing B- and C-subunits are also observed during self-assembly of nonicosahedral capsules; however, they anneal to hexamers in the final nonicosahedral capsules. Although formed in significantly smaller numbers than icosahedral capsids, nonicosahedral capsules are consistently observed in our simulations in which the building blocks of the coat proteins are all either monomers, dimers, or trimers (Figure 2). Nonicosahedral capsules are relatively stable even upon heating up to 381 K . However, since they are more susceptible to structural disruptions because of the strained conformations of the hexameric dislocation, they disassemble more readily than their icosahedral counterparts at higher temperatures (SI, Figure 8). Similar to the $T = 1$ system, we also observe the self-assembly of conical capsules that share the same morphology.

Caspar and Klug in their seminal work on the principle of quasi-equivalence² predicted that the most likely aberrant structures of lower symmetry, yet with similar diameter and surface structure to icosahedral virus particles, to be tubular capsules. The formation of icosahedral capsids and tubular capsules has also been predicted to occur by Bruinsma et al.⁹ and observed experimentally in various *in vitro* assembly systems such as $T = 3$ plant viruses (brome mosaic⁴² and cowpea chlorotic mottle virus),⁴³ $T = 7$ viruses (polyomavirus,⁴⁴

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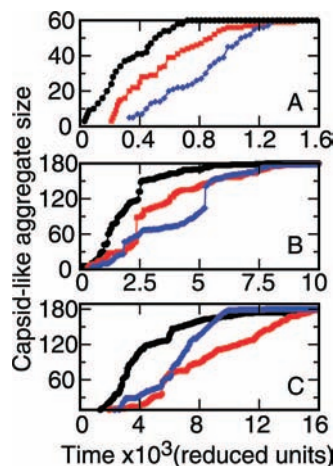


Figure 3. Time-dependent aggregate size of species that grow into complete capsids. Three representative growth curves (red, blue, black) are illustrated for (A) a $T = 1$ system at $86.5 \mu\text{M}$ and 308 K , (B) a $T = 3$ system at $86.5 \mu\text{M}$ and 308 K and (C) a $T = 3$ system at $21.7 \mu\text{M}$ and 290 K to show that condition-dependent growth yields kinetic mechanisms comprising predominantly monomer addition (A and C) and large partial capsid collapse (B).

simian virus 40,⁴⁵ and papillomavirus⁴⁶ and bacteriophage $\phi 29$.⁴⁷ Our $T = 1$ angular and tubular capsules are identical to oblong flock house virus structures, which were experimentally observed by Dong et al.²⁴ and confirmed by Chen et al.²³ Oblate capsules have been seen in the $T = 1$ alfalfa mosaic virus by Cusack et al.⁴⁸ Twisted capsules, to our knowledge, are reported here for the first time; however, we suspect that they are often mistakenly identified as either tubular capsules or enlarged icosahedral capsids because of their similar size and shape. Conical capsules and a variety of spherical and cylindrical structures have also been experimentally observed in retroviral capsids including HIV-1 by Ganser-Pornillos et al.⁴⁹ and examined theoretically with simple continuum elastic theory by Nguyen et al.²² Our findings taken with those just noted reinforce the notion that structural polymorphism is inherent to the nature of assembled coat proteins and that condition-dependent kinetic mechanisms play an important role in determining the various structures of viral capsids.

Kinetic Mechanisms of Icosahedral Capsid and Nonicosahedral Capsule Self-Assembly. The mechanisms for the self-assembly of $T = 1$ and $T = 3$ icosahedral capsids at $86.5 \mu\text{M}$ and 308 K are remarkably different from one another. The formation of $T = 1$ capsids is governed by elementary kinetics via addition of predominately monomers and occasionally small oligomers onto growing structures, as indicated in Figure 3A by the continuity of the particle growth versus simulation time curves for individual simulations. Even though the coat protein concentration is relatively high compared to that utilized in experiments, the data in Figure 3A indicate that there are three distinctive phases of assembly involving nucleation, rapid

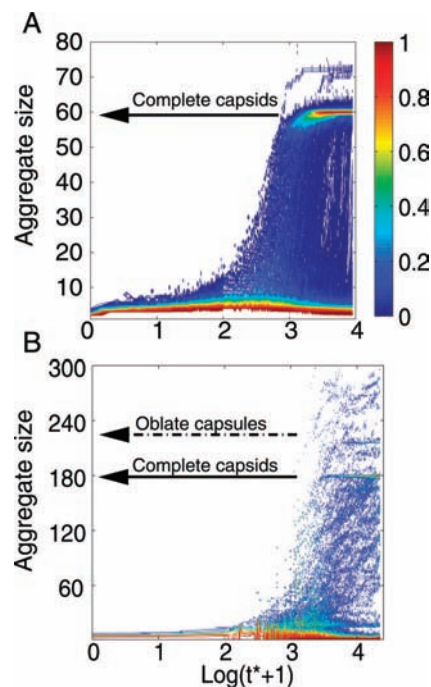


Figure 4. Difference in the kinetic assembly mechanism for $T = 1$ and $T = 3$ systems under analogous conditions is shown by the probability of forming at least one aggregate of a certain size as a function of time. The results are obtained from 100 independent simulations at $86.5 \mu\text{M}$ and 308 K for (A) $T = 1$ and (B) $T = 3$ systems.

growth, and completion. Accumulated data from 100 simulations under the same conditions shown in Figure 4A indeed confirm the nucleation aspect of capsid assembly. Figure 4A shows that the early stage of self-assembly of $T = 1$ capsids is dominated by low order aggregates. Once nuclei are formed, such intermediates are transient and proceed rapidly to form aggregates of larger size and eventually complete capsids. At the end of each simulation, there is a partitioning between complete capsids and free monomers. This finding is similarly observed in light scattering and size exclusion chromatography experiments that monitor capsid assembly^{8,50,51} and the two generic thermodynamic–kinetic models that were developed by Zlotnick and co-workers.^{8,52,53} Moreover, the kinetic mechanism for the $T = 1$ capsid self-assembly that is observed in our simulations is also seen in simplified model studies by Zhang and Schwartz,¹⁶ Hagan and Chandler,¹⁷ and our previous studies¹⁸ that represent either three coplanar proteins as a capsomer or an individual protein as a structural unit. However, there is a significant difference between our results¹⁸ and those observed from the single-bead studies^{16,17} during the last stage of capsid assembly which involves the addition of the final subunits into the growing structure. Protein subunits that are modeled as single spherical beads are not sterically hindered and thus are more easily inserted into the growing structure, whereas our protein subunits that are modeled as trapezoidal structures have to adjust themselves to a specific orientation relative to the capsid before the insertion step. Because of such high entropic costs, the

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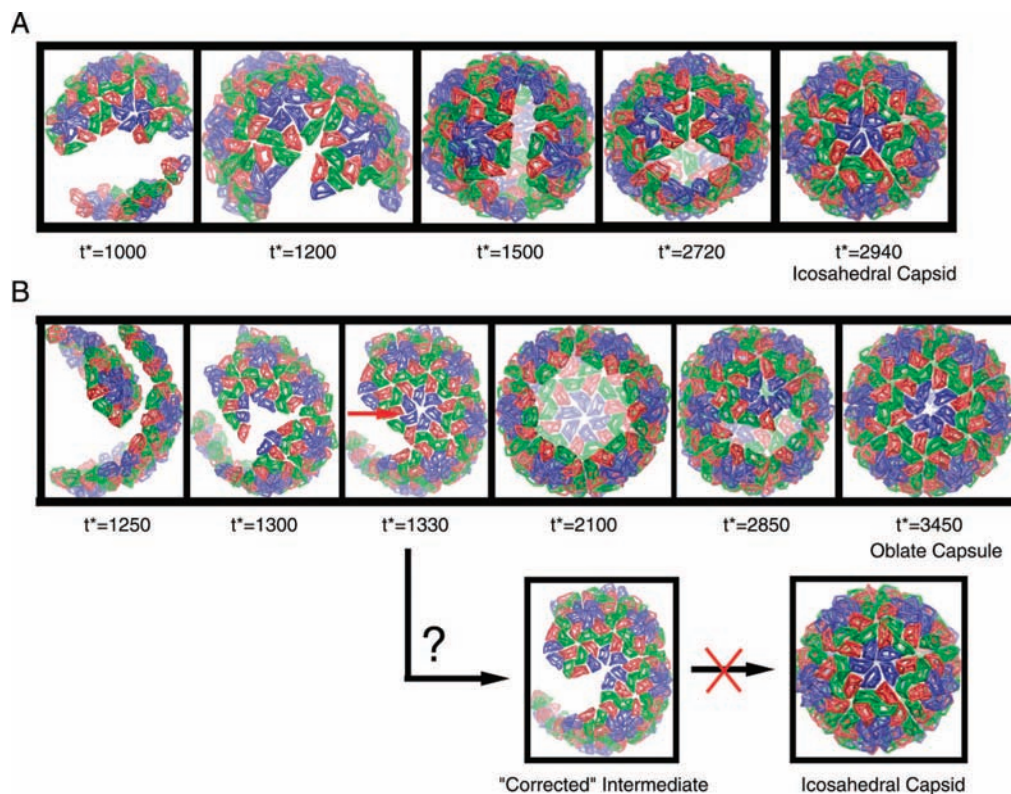


Figure 5. Representative stages of aggregate growth of a (A) $T = 3$ icosahedral capsid and (B) oblate capsule at $86.5 \mu\text{M}$ and 308 K . The red arrow shows the first hexameric dislocation resulting from a collapse event during the self-assembly of the oblate capsule. If the hexameric dislocation was allowed to switch to a pentamer so the combined structure could grow into an icosahedral capsid, three extra protein subunits next to the red arrow have to be removed. Such transformation requires overcoming a relatively high free energy barrier and thus is an event of low probability.

amount of time needed to add each of the final subunits substantially increases as the growing structure approaches completion.

In contrast, $T = 3$ icosahedral capsid self-assembly at $86.5 \mu\text{M}$ and 308 K utilizes a mechanism in which preformed aggregates of intermediate sizes combine. The large jumps in the growth curves in Figure 3B indicate that aggregates ranging from 10 to 40 proteins join the growing structures. Once these large aggregates combine, continual growth occurs at multiple points simultaneously with separate long, relatively flexible, “arms” that later merge to close the structure (Figure 5A). This structural flexibility and collapse of conjoining faces can give rise to the formation of the hexameric dislocations that lead to nonicosahedral capsules. Kinetic data from 100 simulations show that self-assembly in the $T = 3$ system involves a relatively large distribution of intermediates of varied sizes (indicated as small red dots in Figure 4B), which collapse onto one another to form either icosahedral capsids or aberrant capsules. At the end of each simulation, there is no clear partitioning between complete capsids and other species since complete capsids, large capsules (predominately oblate capsules), and intermediates of various aggregate sizes (at a low population) coexist with the free monomers.

Self-assembly of nonicosahedral capsules in both $T = 1$ and $T = 3$ systems involve the critical early step of forming hexameric dislocations, which arise during the collapse of intermediates of significant sizes containing noncomplementary edges. For example, the formation of an oblate capsule (Figure 5B) is initiated by the collapse of two isolated oligomers containing noncomplementary edges, resulting in a trapped hexamer of A-subunits, which propagates the formation of a

flat surface containing six pentamers of A-subunits in a ring rounding off at the edge. This process is replicated in reverse in forming the other symmetric half by first growing another ring containing six pentamers forcing B- and C-subunits at the growing edge to be on the same plane so that another hexamer of A-subunits is filled in to enclose the structure. In general, the critical step of forming the first hexameric dislocation instigates a series of coordinated events that yield additional hexameric dislocations, whose locations relative to the initial hexamers determine whether the growing structure can form an enclosed ordered structure or open misaggregate. Specifically, the formation of extra hexameric dislocations at well-defined positions creates nonicosahedral capsules, whereas the formation of randomly located dislocations leads to open misaggregates lacking any global symmetry. Additional hexameric dislocations are often formed to relieve the strain caused by the disjointed junctions between concave surfaces and flat initial hexameric dislocations by pulling an existing pentamer apart to insert another A-subunit or by filling in a flat hole to enclose a growing structure.

Interestingly, even though different simulations proceed from configurations of all monomers, dimers, or trimers of the coat proteins, the results from these simulations exhibit the same behavior not only in the end point structures and their population distributions but also in the kinetic mechanisms (data not shown). This implies that when the initial supply of coat proteins is limited, as long as subunits are started as either individual proteins or uniform capsomers of the same aggregate size, self-assembly of both icosahedral capsids and nonicosahedral capsules proceed via the same kinetic mechanisms, which

involves both sequential addition of individual building blocks and condensation of preformed intermediates.

Toward Controlled Self-Assembly by Searching for the Optimal Assembly Condition. Since the rapid establishment of a high population of partial structures appears to lead to the formation of large nonicosahedral capsules via the collapse–growth mechanism, alternative conditions for particle growth that minimizes the population of large partial structures and thus reduces the probability of forming structures with kinetically trapped hexameric dislocations will likely increase the yield of $T = 3$ icosahedral particles. Assembly initiated from a lower concentration of coat protein ($21.7 \mu\text{M}$) and at lower temperature (290 K) (Figure 3C) appears to limit the rapid growth of multiple large aggregates and yield monomer addition driven growth.⁸ Indeed, by shifting to an alternative region in the phase diagram for particle growth, we find a higher population of icosahedral capsids assembled (SI, Figure 10) albeit following significantly longer incubation periods. This points to the control of assembly conditions as a key strategy for the control of assembly products and the improvement of laboratory and manufacturing yields, which may serve as an instrumental means in increasing the potency of cervical cancer vaccines.⁶

The difference in the optimal conditions between $T = 1$ and $T = 3$ capsid assembly is an inherent property of the capsid size. Since $T = 1$ capsids are relatively small, requiring 60 subunits arranged in 12 pentamers that are concave, their growing intermediates are relatively enclosed and this inhibits association with other intermediates. This allows partial structures to grow into complete capsids over a wide range of protein concentrations but over a narrow range of temperature, as previously reported.¹⁸ Therefore, by just lowering the temperature from 308 to 290 K, which in effect strengthens the interfacial interactions and increases the number of nuclei or intermediates growing in the system, the assembly mechanism switches from monomer addition to oligomer collapse. In contrast, $T = 3$ capsids are much larger, requiring 180 subunits arranged in 12 pentamers and 20 hexamers that are relatively flat, and the residence time of their growing intermediates, which are relatively open, is longer. Therefore, intermediates in $T = 3$ systems are more susceptible to association at high protein concentrations such as $86.5 \mu\text{M}$. Diluting the protein concentration to $21.7 \mu\text{M}$ switches the assembly mechanism from oligomer collapse to monomer addition. Since all interfaces are modeled with the same interaction strength in this study, a richer picture of self-assembly would be anticipated by incorporating differential interface potentials, as demonstrated by Sweeney et al.⁵⁴ Examination of the kinetic mechanism as a function of the differential interface potential, protein concentration, and temperature will be the subject of a future publication.

Observation of Misassembled Aggregated or “Monster Particles” at Extreme Conditions. Increased protein concentration and lower temperatures, at the other extreme, e.g., $173 \mu\text{M}$ and 264 K , produce misassembled aggregates in simulations of both $T = 1$ and $T = 3$ systems. In this case, assembly is initiated too many times yielding an overabundance of nuclei that cannot proceed to completion as capsids and instead collapse to form non-native contacts thereby creating oversized misassembled aggregates.^{8,17,18,55} This specific situation in which kinetic pathways are pertinent to self-assembly is an example of a generally appreciated concept.⁵⁶ In particular, a completed self-

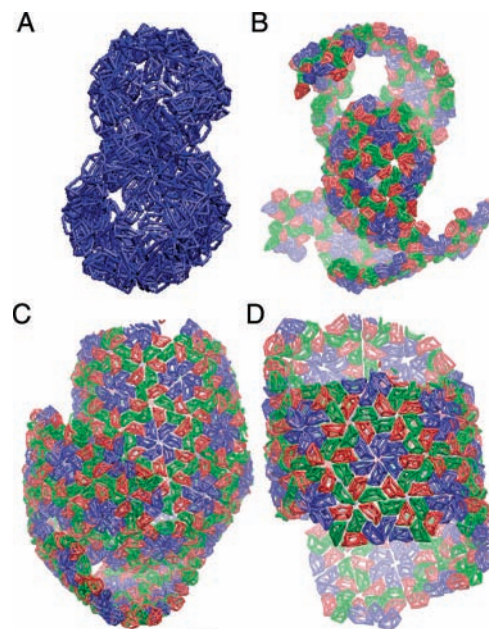


Figure 6. Snapshots of assemblies that are as follows: (A) relatively enclosed monster particle obtained at $173 \mu\text{M}$ and 264 K from the $T = 1$ system; (B) large and spiral monster particle obtained at $173 \mu\text{M}$ and 264 K from the $T = 3$ system; (C) large, open, layered, and disordered when A-subunits are replaced by the averaged structure of A-, B-, and C-subunits; and (D) large, open, and ordered when A-subunits are replaced by the averaged structure of B- and C-subunits at $86.5 \mu\text{M}$ and 308 K for the $T = 3$ system.

assembled cluster is composed of many units, and there are many pathways by which they can cluster. When intermediate structures initially form, they must have time to organize into an arrangement that is amenable to further assembly. If there is insufficient time to establish a local equilibrium, mistaken assemblies will occur when binding energies are too large or subunit concentrations are too high. In such cases, thermal agitation cannot anneal the structure before another subunit attaches to the cluster. This phenomenon was first analyzed by Schwartz et al.⁵⁷ and Hagan and Chandler¹⁷ and was further illustrated by Nguyen et al.¹⁸ More recently, a means of quantifying the phenomenon through measurements of fluctuation–dissipation ratios has been proposed.⁵⁸

Generally, we observe that the misassembled aggregates, also known as “monster particles”, emerging from the $T = 1$ systems differ from those in $T = 3$ systems (Figure 6A and B). The $T = 1$ monster particles tend to contain a few partial capsids and are relatively enclosed, remarkably resembling Turnip crinkle virus monster particles.³⁵ $T = 3$ misassembled aggregates have a more complex architecture that resembles the spiral structures of bacteriophage P22 monster particles.⁵⁹ This diversity is a direct consequence of the inherent difference in the overall structure of the $T = 1$ subunits, which form only pentameric concave capsomers, and $T = 3$ subunits, which assemble as a competition between these same pentameric concave capsomers and flat hexameric capsomers. This competition, and the fact that $T = 3$ subunits can become kinetically trapped at low

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temperatures in helix-like clusters with more than six B- and C-subunits arranged alternately in spiral motifs, gives rise to additional nonspherical appendages hanging off the sides of the $T = 3$ derived monster particles.

Coat Protein Engineering. The geometric differences in our structural units mirror the small variance observed in the structure of proteins in pentameric and hexameric capsomers from many icosahedral capsid crystal structures of various viruses (ranging from $T = 3$ to 13).⁴⁰ In fact, for capsids without any apparent intersubunit holes or overlaps, the structures of the same protein in either pentameric or hexameric positions often differ by only about 1.0 Å rmsd in C_α atoms. These subtle conformational differences can be exploited in therapeutic development to interfere with the self-assembly of viable viral capsids. For example, when A-subunits are replaced by the averaged structure of A-, B-, and C-subunits, meaning that the A-subunit's ability to form pentamers is significantly reduced while its ability to form hexamers is enhanced, assemblies at 86.5 μM and 308 K are large, open, layered, and disordered aggregates containing pentamers and hexamers at random locations (Figure 6C). In this case, too many missteps occur for the growing structures to recover. Moreover, replacing the A-subunits by the averaged structure of the B- and C-subunits, to produce strongly biased hexameric capsomer forming species, results in assembly end points that are large, open, and ordered aggregates containing only hexamers (Figure 6D). These sheet-like aggregates grow and wrap around to form open-ended nanotubes, which could serve as a source of new biomaterials. These results provide the potential for direct testing and may already be confirmed in recent experiments by Stray et al.,⁵⁵ who show that one can alter the yield of capsid particles by binding a "wedge" between the protein interfaces and hence artificially force specific interfaces into the assembly process.

Discussion

In systems comprised of both pentameric and hexameric capsomers, i.e., for $T \geq 3$, the switching of coat proteins between conformations that are poised to form either a pentameric or hexameric capsomer must occur during assembly, since all protein subunits are chemically identical.³¹ We account for this switching mechanism in our $T = 3$ assembly studies by (1) explicitly representing protein subunits in a pre-equilibrium of the three predetermined conformations and (2) imposing specific interactions between protein subunits at appropriate interfaces. This approach is able to regulate the formation of pentamers and hexamers at well-defined locations to yield icosahedral capsids based only on the geometric shapes and protein-protein interactions of the subunits. However, when the pre-equilibrium is shifted to favor pentamer-templated protein A-subunits, the proclivity for five-to-six (and higher) symmetric dislocations increases resulting in the formation of oblate and other aberrant structures (SI, Figure 10). One notable type of structure observed under these conditions are monster particles that resemble oblate and other nonicosahedral capsules; however, they are not completely enclosed due to the presence of too many A-subunits that grow on each side of the opening.

When accounting for the conformational switching mechanism, we assume that it must occur in the bulk as a monomeric species, possibly instantly before the protein subunit is added onto the growing structure. Once assembled, even if autostery could take place between protein subunits that are in the aggregated state, spontaneous switching between a pentamer and a hexamer is unlikely since such a highly cooperative

process that involves five to six protein subunits would require overcoming a large energy barrier for either removing one extra protein subunit when a hexamer is converted into a pentamer or adding an additional protein subunit when a pentamer is converted into a hexamer. In the first case, not only does one subunit have to be removed from the hexamer but also the protein subunits that are attached to the excised subunit must be removed as well (Figure 5B); therefore, the probability that such a transformation would occur decreases as the number of the attached subunits increases. Consequently, once sizable intermediate aggregates collapse into one another, the combined structure is significantly stable as it keeps growing into nonicosahedral capsules. In the latter case, adding an additional protein subunit onto a closed pentamer requires pulling one of its interfaces apart by breaking not only those interactions present in the pentamer but also those interactions of the protein subunits that are attached to the pentamer along that interface as well. Therefore, spontaneous switching between a pentamer and a hexamer in the aggregated state is unlikely to occur unless with the help of auxiliary machinery or drastic changes in the environmental conditions.

The self-assembly of nonicosahedral capsules is a consequence of an off-pathway mechanism that is prevalent under nonoptimal conditions rather than the result of improperly accounting for autostery. In $T = 1$ systems, where the conformational switch mechanism is unnecessary in capsid self-assembly since $T = 1$ capsids contain only one conformation of the coat proteins, the same type of nonicosahedral capsules as those observed in $T = 3$ systems emerges. Similarly, *in vitro* experiments by Dong et al.²⁴ reveal that when the molecular switch of the $T = 3$ flock house virus is deleted, icosahedral capsids of $T = 1$ size are observed in addition to multiple types of oblong capsules that are larger than $T = 1$ capsids and smaller than $T = 3$ capsids. Analysis of these oblong capsules indicates that they share the same morphology and size as those observed from our simulations. These results suggest that the conformational switch mechanism would not be able to prevent the self-assembly of polymorphic structures in $T = 3$ systems once hexameric dislocations have been kinetically trapped.

Conclusion

The combination of coarse-grained models, which capture the essential geometry and interaction details of real coat proteins yet are simple enough to allow the dynamical simulation of systems containing many such proteins, with discontinuous molecular dynamics,³⁶ have been used to simulate the spontaneous formation of supramolecular structures of large $T = 1$ and $T = 3$ viral capsids (without the genomic contents) initiated from random configurations of only protein monomers, dimers, or trimers. Our findings demonstrate that structural polymorphism in the end point structures is an inherent property of coat proteins, is independent of the morphology of constituent subunits, and arises from condition-dependent kinetic mechanisms that are determined by initial assembly conditions related to protein concentration and temperature. Based on the ubiquitous nature of nonicosahedral capsules observed in our simulations, we predict that such capsules also occur in $T > 3$ systems having precise numbers of $N = 60 \cdot T + 6 \cdot T \cdot D$ subunits.⁶⁰ We also show that the assembly of icosahedral capsids and other enclosed nonicosahedral capsules can be controlled by fine-tuning assembly conditions. Moreover, we

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illustrate that conformational switching within individual coat proteins controls their ability to form pentameric capsomers, altering the formation of enclosed structures and interfering with the self-assembly of viable virus particles. Simulation studies as described here and continuing efforts to examine capsid self-assembly in specific virus systems provide new informative tools for potential strategies in antiviral development, protein design, and the engineering of novel biomaterials.

The genomic content and/or other auxiliary components such as scaffold proteins play an important role in the self-assembly of full viruses. They may serve as a template or a means to control the formation of icosahedral capsids and thus prevent the formation of polymorphic capsules. The models that we have developed in this study can be used to further examine the role

of the genomic content and scaffold proteins in improving the fidelity of structural morphology in viral capsids.

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Supporting Information Available: Four movies showing oblate, angular, twisted, and tubular capsules from $T = 3$ simulations; additional analysis on icosahedral capsids, structural stability, and alternative assembly conditions. This material is available free of charge via the Internet at <http://pubs.acs.org>.

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